

# Control System Implementation

## Hardware implementation



Mekatronik 2005

## Electronic Control systems are also: *Members of the Mechatronic Systems*

- Concurrent design (Top-down approach?)
- Mechanic compatibility
- Solve the actual task
- Separating the control system design from the mechanic "target" is a risky business

Mekatronik 2005

## Printed Circuit Boards (PCBs) - #1

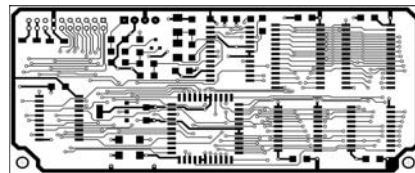
- **Material requirements**
  - Mech. stress
  - Electr. isolation (also at high frequency)
  - Thermal conductivity
- **Materials used**
  - Glass fiber dominating today
  - Ceramic materials for high thermal conductivity
  - Polymer materials for flexible PCB:s

Mekatronik 2005

## Printed Circuit Boards (PCBs) - #2

### PCB manufacturing process (simplified)

- Copper foil attached (5-35  $\mu\text{m}$ )
- Photo resistive coating
- Exposure with photo mask
- Develop pattern
- Etching



Conductive copper pattern remains on board

Mekatronik 2005

## Printed Circuit Boards (PCBs) - #3

- Through-plated via-holes connect the top and bottom layer
- Multilayer boards - same principle but thin layers pressed together. Then through-plated
- A lot of requirements can be met with modern PCB technology. **But it's important to specify!**

Mekatronik 2005

## Electronic systems exposed to Environmental Factors

- Mechanical stress
  - Direct forces and torque can usually be avoided
  - Acceleration might be more difficult to handle
- Temperature
  - Check the classification of your components. **Commercial**, **Industrial** or **(Military)**.
- Humidity
  - Coating , encapsuling.
- EMC

Mekatronik 2005

## Analyzing the Control Task

- Task complexity
  - Understand the problem
  - Where is it possible to install control system parts
  - Centralized/ distributed control
- Speed requirements
  - Sensor/actuator time scheduling
  - Computational power requirements

A mutual understanding of Mechanical/Electrical design often gives the opportunity of solving a difficult problem by a minor redesign "on the other side"

Mekatronik 2005

## Possible Solutions for the control Task

- Discrete analog circuit
- Discrete digital circuit
- ASIC (Application Specific IC)
- Programmable logic IC (PLD or FPGA)
- Computing unit (microcontroller, DSP...)

Mekatronik 2005

## Discrete Analog Circuits - Opportunities

- Operational amplifiers (OP-amp)
  - Add, subtract
  - Filter
  - Derivative, integration
- Analog computation components
  - Multiplication
  - Logarithmic functions
  - Rms-detection...

Mekatronik 2005

## Discrete Analog Circuits - Summary

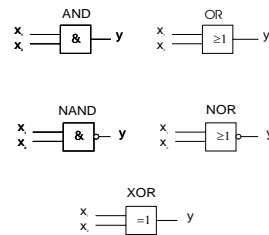
- +
  - Continuous operation
  - Fast (?!) processing of analog signals
  - Cost effective
- - Logical conditions difficult to include
  - Interfacing problems
  - Experienced engineer required

Mekatronik 2005

## Discrete Digital Circuits

Gates, flip-flops, counters, registers...

- Simple logical problems
- Primary use today as support ("glue") to more advanced digital systems
- High speed applications



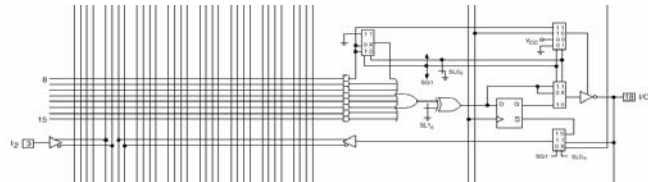
Mekatronik 2005

## PLD - Programmable Logic Devices

- Logical function programmable. Several languages e.g. VHDL
- AND/OR -planes
- Pin mapping programmable
- Internal flip/flops makes internal state machines possible
- Almost the same speed as discrete logic
  
- Starts at discrete logic replacement at < 1\$ cost/unit
- Large devices with several sub-blocks and interconnection matrixes

Mekatronik 2005

## PLD structure example



GAL16V8 with a fraction of the programmable matrix and a macro cell

Mekatronik 2005

## FPGA

Field Programmable Gate Arrays

- Larger than PLD but the borderline is not absolutely clear
- Programmable logic structures
- Several development languages e.g. VHDL
- Can include (Flash) memory, DSP .....
- E.g. a large FPGA can very well be used to implement a microcontroller

Mekatronik 2005

# ASIC

## Application Specific Integrated Circuit

- Full freedom. Analog or digital or mixed signal.
- Design supported by large libraries (IP: Intellectual Property)
- Design at transistor level possible
- Only used in large scale production since development costs are high. However, price per unit is low.

Mekatronik 2005

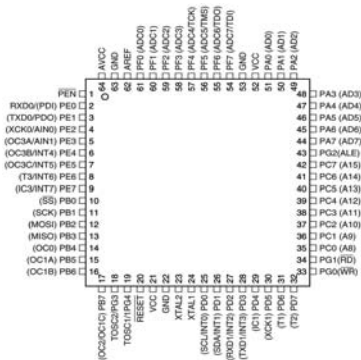
# Microcontroller

- Single chip computer. Complete system:
  - CPU
  - Memory
  - I/O devices including analog
  - Timer
- Few external components (if any)
- Low cost (< 1\$ and upwards)

Mekatronik 2005



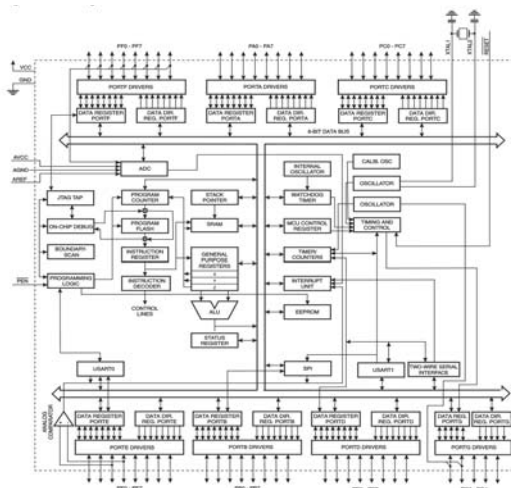
# AVR ATmega128 - as an example



- ...
- Up to 16 MIPS Throughput at 16 MHz
- On-chip 2-cycle Multiplier
- Nonvolatile Program and Data Memories
- 128K Bytes of In-System Reprogrammable Flash
- ...
- 4K Bytes Internal SRAM
- ...
- Two 8-bit Timer/Counters with Separate Prescalers and Compare Modes
- Two Expanded 16-bit Timer/Counters with Separate Prescaler, Compare Mode
- ...
- Real Time Counter with Separate Oscillator
- Two 8-bit PWM Channels
- 6 PWM Channels with Programmable Resolution from 2 to 16 Bits
- Output Compare Modulator
- 8-channel, 10-bit ADC
- 8 Single-ended Channels
- 7 Differential Channels
- 2 Differential Channels with Programmable Gain at 1x, 10x, or 200x
- Dual Programmable Serial USARTs
- Master/Slave SPI Serial Interface
- Programmable Watchdog Timer with On-chip Oscillator
- On-chip Analog Comparator
- ...

Mekatronik 2005

# AVR ATmega128 - overview



Mekatronik 2005

## DSP

### Digital Signal Processor

- Especially well suited architecture for signal processing (e.g. Filtering, FFT...)
- Few internal operations in each instruction gives a high execution rate
- The internal datapath can support a parallel execution at several stages.

Mekatronik 2005

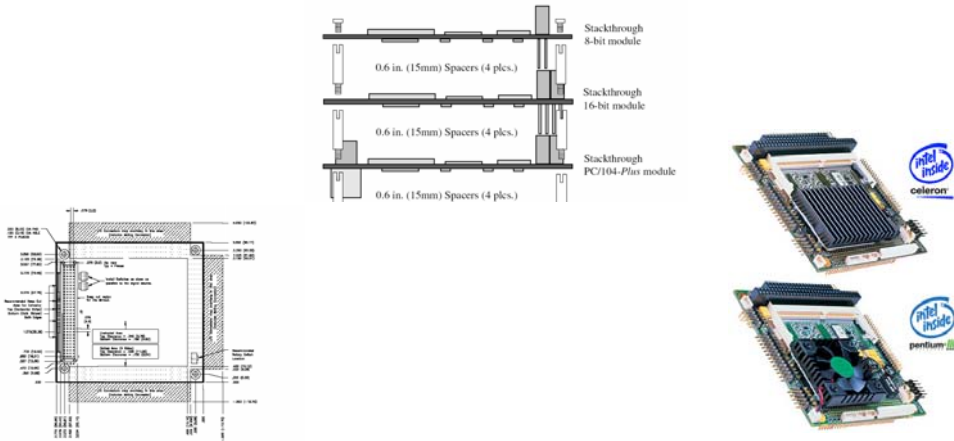
## Embedded PC

- The success of the PC architecture gives several economical advantages
- Stability problems not due to hardware
- Several standards for embedded PC exists (e.g. PC104)
- It is also possible to use an "industrial PC box" without any peripheral devices but equipped with LAN- and fieldbus-connections

Mekatronik 2005

## PC-104 standard for embedded PC

<http://www.pc104.org>



Mekatronik 2005

## Various formats for embedded PC



Compact PCI



Free format  
(PC104 host)

Mekatronik 2005

## Industrial PC – Product Example



Mekatronik 2005

## PLC

### Programmable Logic Controller

- The fundamental industrial control system of the latest decades
- Originally only logic control but nowadays analog I/O and PID-loops
- Programming languages (IEC 61131-3)
  - Ladder Diagram (LD)
  - Function Block Diagram (FBD)
  - Instruction List (IL)
  - Structured Text (ST)
  - Sequential Function Chart (SFC)



Mekatronik 2005

## Memory

- SRAM - Read/Write, Volatile, Static design
- DRAM - Read/Write, Volatile, Need cyclic refresh
- ROM - Read. Programmed in production
- PROM - Read, User programmable
- EPROM - Read, UV-Erasable user programmable
- EEPROM -Read, Electrically erasable
- Flash -Type of EEPROM

Rotating hard-disks are often avoided in embedded applications and replaced by disk-emulating EEPROM memories (Flash disk).

Mekatronik 2005

## Analog signals

- D/A conversion
  - Multiplying converter
  - PWM + LowPass filter (low cost solution)
- A/D-conversion
  - Successive approximation (microcontrollers)
  - Flash (fast)
  - Dual slope (high accuracy, slow)
  - Sigma/Delta

Mekatronik 2005

## Sampling

- Sampling frequency is a critical factor
- The system has no idea what happened between the sampling instants
- Remember Nyquist frequency:  $f_N = f_s/2$   
(practically a factor 5-10 applied)
- Use filters

Mekatronik 2005

## Galvanic Separation

When?

- Connecting to power systems
- EMC problem reduction when connecting different systems
- Grounding problem elimination

How?

- Relays
- Optocouplers (LED - phototransistor)
- Opto-fiber
- Isolation Amplifier (analog)

Mekatronik 2005

# Communication

- Communication often becomes a key issue in the design



Mekatronik 2005

# Power Supply

- SMPS (Switch Mode Power supply) technology development is dramatically changing the situation
- Options
  - Power grid supply
  - Step-up conversion
  - Step-down conversion
- To make a regulated 3.3 or 5 V supply from a 1.2 V battery cell costs < 3\$

Mekatronik 2005

## Power supply examples

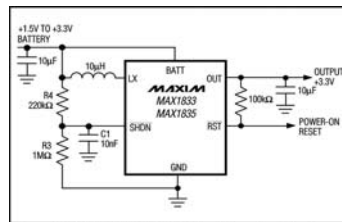


Figure 1a. MAX1833/MAX1835 Typical Operating Circuit

Produces 3.3 V, 150mA. IC size 3x3mm.  
IC costs 1\$52 in 1k quantity

Mekatronik 2005